

**Final - Computer Science 2 (2021-22)**

**Time: 3 hours.**

*Attempt all questions, giving proper explanations.*

1. Consider the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 2 & 2 \\ 1 & 2 & 3 & 3 \\ 1 & 2 & 3 & 4 \end{bmatrix}$$

- (a) Apply the first iteration of the *classical Jacobi method*: Find the orthogonal matrix  $\mathbf{P}$  such that the (3, 4)th entry of  $\mathbf{A}^{(1)} := \mathbf{P}^T \mathbf{A} \mathbf{P}$  is 0, and write down  $\mathbf{A}^{(1)}$ . [5 marks]
- (b) For a matrix  $\mathbf{M}$  let

$$L(\mathbf{M}) := \sum_{i \neq j} |m_{ij}|^2$$

be the sum of squares of the off-diagonal entries of  $\mathbf{M}$ . If  $\mathbf{A}^{(k)}$ ,  $k \geq 0$  are the successive iterates of the classical Jacobi method, show that

$$L(\mathbf{A}^{(k+1)}) < L(\mathbf{A}^{(k)}). \quad [4 \text{ marks}]$$

2. Consider a matrix  $\mathbf{A} = (a_{ij}) \in \mathbb{C}^{n \times n}$  with  $n \geq 2$ . Consider the Gerschgorin discs

$$D_i = \{z \in \mathbb{C} : |z - a_{ii}| \leq R_i(\mathbf{A})\},$$

where  $R_i(\mathbf{A}) := \sum_{\substack{j=1 \\ j \neq i}}^n |a_{ij}|$ .

- (a) State Gerschgorin's first and second theorems. (no need to prove) [4 marks]
- (b) Now let  $\mathbf{A} \in \mathbb{R}^{n \times n}$  be a symmetric matrix. Assume Gerschgorin's first and second theorems, and  $\max_i R_i(\mathbf{A}^{(k)}) \xrightarrow{k \rightarrow \infty} 0$  for the iterates  $\mathbf{A}^{(k)}$  in the classical Jacobi method. Let  $b_1^{(k)} \leq b_2^{(k)} \leq \dots \leq b_n^{(k)}$  be the ordering of the diagonal entries of  $\mathbf{A}^{(k)}$  and  $\lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n$  be the eigenvalues of  $\mathbf{A}$ . Argue that  $(b_1^{(k)}, b_2^{(k)}, \dots, b_n^{(k)}) \xrightarrow{k \rightarrow \infty} (\lambda_1, \lambda_2, \dots, \lambda_n)$ . [4 marks]
3. (a) Find the polynomial  $p_3$  of degree 3 which passes through the points  $(0, 1)$ ,  $(1, e)$ ,  $(2, e^4)$ ,  $(3, e^9)$ . [3 marks]
- (b) Give the best possible bound on  $\sup_{x \in [0, 4]} |e^{x^2} - p_3(x)|$ . [3 marks]
- (c) Find the Newton-Cotes approximation for  $\int_0^3 e^{x^2} dx$  using the quadrature points  $0, 1, 2, 3$ . [2 marks]
- (d) Give the best possible bound on the error in the approximation in 3c. [2 marks]
4. Let  $f : [0, 1] \rightarrow \mathbf{R}$  be an infinitely differentiable function. The Hermite interpolation polynomial approximating a function  $f$  at the interpolation points  $0 \leq x_0 < x_1 < \dots < x_n \leq 1$  is a polynomial of degree  $2n + 1$  given by

$$p_{2n+1}(x) = \sum_{k=0}^n H_k(x) f(x_k) + \sum_{k=0}^n K_k(x) f'(x_k),$$

where

$$H_k(x) = [L_k(x)]^2 \left[ 1 - 2L'_k(x_k) \cdot (x - x_k) \right],$$
$$K_k(x) = [L_k(x)]^2 (x - x_k).$$

Here

$$L_k(x) = \prod_{\substack{i=0 \\ i \neq k}}^n \left( \frac{x - x_i}{x_k - x_i} \right).$$

We showed in class that by choosing  $x_0, x_1, \dots, x_n$  to be the distinct zeroes of  $\phi_{n+1}$ , the  $(n+1)$ th orthogonal polynomial in  $[0, 1]$ , one obtains

$$\int_0^1 p_{2n+1}(x) dx = \sum_{k=0}^n W_k f(x_k),$$

where

$$W_k = \int_0^1 [L_k(x)]^2 dx.$$

(a) Show that for this choice of  $x_0 < x_1 < \dots < x_n$  we have

$$\int_0^1 [L_k(x)]^2 dx = \int_0^1 [L_k(x)] dx \quad \text{for each } k. \quad [5 \text{ marks}]$$

(b) Show that for this choice of  $x_0 < x_1 < \dots < x_n$  we have

$$\int_0^1 f(x) dx = \sum_{k=0}^n W_k f(x_k)$$

whenever  $f \in \mathcal{P}_{2n+1}$  (the collection of polynomials of degree at most  $2n+1$ ). [2 marks]

(c) Let  $q_n$  be the Lagrange polynomial of degree  $n$  approximating  $f$  at the interpolation points  $x_0, x_1, \dots, x_n$  chosen above. Show that

$$\int_0^1 f(x) dx = \int_0^1 q_n(x) dx$$

whenever  $f \in \mathcal{P}_{2n+1}$ . [3 marks]

(d) For  $n = 1$  find  $x_0, x_1$ . [4 marks]

(e) Explain why the Gauss quadrature rule for  $n = 1$  is better than the trapezium rule. [2 marks]

5. Let  $f : [0, T] \times \mathbf{R} \rightarrow \mathbf{R}$  be such that

- $f$  is continuous on  $[0, T] \times \mathbf{R}$ ,
- $\frac{\partial f}{\partial t}$  and  $\frac{\partial f}{\partial x}$  are bounded on  $[0, T] \times \mathbf{R}$ .

Consider the solution  $x : [0, T] \rightarrow \mathbf{R}$  of the differential equation

$$\begin{aligned} \frac{dx}{dt} &= f(t, x), \\ x(0) &= \alpha. \end{aligned}$$

Split the interval  $[0, T]$  into subintervals of size  $h > 0$  so that  $0 = t_0 < t_1 < \dots < t_n = T$  with  $t_i = ih$  are the grid points. Consider the Euler approximation of  $x$  on the grid points :

$$\begin{aligned} \tilde{x}(t_i) &= \tilde{x}(t_{i-1}) + f(t_{i-1}, \tilde{x}(t_{i-1})), \quad 1 \leq i \leq n \\ \tilde{x}(0) &= \alpha. \end{aligned}$$

Prove in detail that  $\sup_i |x(t_i) - \tilde{x}(t_i)| = O(h)$  as  $h \rightarrow 0$ . [7 marks]